



Andrea Pizzetti

PhD in Aerospace Engineering

Expertise

Modeling & Simulation • Verification & Validation • HIL Testing • Vision-Based Navigation • Radiometry • Rendering • Autonomous Systems • Statistics & Probability

Coding

MATLAB

Simulink & Stateflow

Python

Java

Software

Office • \LaTeX • Git • Confluence • Jira • Blender

Languages

Italian

English C1

Spanish B2

French A1

Interests

► Piano

Work Experience

VBN Engineer

Politecnico di Milano | Milan, Italy

nov/2023 - today

- *StarNAV*. Radiometric calibration of the HIL optical facility. Generation of a dataset of STR images.

GNC/AOCS Engineer

Deimos Space | Madrid, Spain

nov/2021 - nov/2023

- *ClearSpace-1*. Development of a flexible modes model for the solar panels and robotic arms. Design of orbital estimator with delay management. Design of fully-magnetic controller for safe mode with adaptive spin-stabilization.
- *SAT4EO*. Simulation and verification of requirements during safe mode. Development of guidance algorithms. Modelling of albedo disturbance effect. Definition of commissioning procedures.
- *DRACO*. Analysis of re-entry trajectory for the design of the Attitude Determination System.
- *Comet Interceptor*. Development of a comet dust flow model. Analytical validation of MC campaign with statistical distributions fitted on empiric data.
- *eAOCS, Cassini, LEO-PNT, Endurance*. Preliminary AOCS analysis and sizing.

AOCS Team Leader

PoliSpace | Milan, Italy

mar/2021 - nov/2021

- Trade-off analysis, definition, design, simulation and tuning of the AOCS for a 1U CubeSat.
- Interaction with CubeSats hardware providers for procurement and funding.
- Selection of the AOCS team (5 students out of 90 applicants), through assessment of multiple-choice tests, CV/Motivational Letter screening and interviews.

Simulation Engineer

PoliMOVE | Milan, Italy

sep/2020 - oct/2021

1st place @ CES, Las Vegas

- Generation and simulation of scenarios for autonomous racing cars in Ansys.
- Implementation and refinement of car behaviours and trigger conditions.
- Development of an automatic pdf report generation tool from race logs.
- Development and simulation of the state machine for transition to the real vehicle.

Education

PhD in Aerospace Engineering

Politecnico di Milano | Milan, Italy

nov/2023 - today

Design of autonomous vision-based navigation systems and PIL/HIL validation in star trackers applied to the detection, tracking and approach of small bodies in far to mid-range regimes.

MSc in Space Engineering

Politecnico di Milano | Milan, Italy

sep/2019 - dec/2021

110/110 Cum Laude

Orbital Mechanics • Spacecraft Attitude & Control • Space Propulsion • Launch Systems • Space Physics • Payload Design • Telecommunication Systems

- ▶ Analog Photography
- ▶ Running & Hiking

Contact

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Milan, Italy

✉ Mail [↗](#)

in LinkedIn [↗](#)

BSc in Aerospace Engineering

Politecnico di Milano | Milan, Italy

102/110

Thermodynamics and Heat Transfer • Applied Numerical Analysis • Aerospace Technologies and Materials • Aerospace Propulsion • Fluid Dynamics • Modelling of Aerospace Structures

sep/2016 - sep/2019

Publications

- Pizzetti, A., Fabrizi, A. (2024). Analytical characterization of the off-pointing probability for a spin-stabilized SC subject to random particle impacts. *Proceedings of the 2024 CEAS EuroGNC conference*. [↗](#)
- Pizzetti, A., Rizza, A., Topputo, F. (2023). Autonomous wheel off-loading strategies for deep-space cubesats. *Aerotecnica Missili & Spazio*, 102(1), 3-15. [↗](#)

Conferences

- **CEAS EuroGNC Conference** | Bristol, 2024
- **ASI CubeSat Workshop** | Rome, 2022
- **XVIII PEGASUS Student Conference** | Pisa, 2022
- **4th Symposium on Space Educational Activities** | Barcelona, 2022
A student-made approach for CubeSat design: the 6S roadmap [↗](#)
Effective student team infrastructure towards CubeSat mission design in pandemic times [↗](#)

Awards

- **8th place at XVIII Pegasus Student Conference** | Pisa, 2022
Selected for publication in a peer-reviewed journal
- **MATLAB Minidrone Competition** | Milan, 2020
Winning team for the development of an autonomous path tracking and landing control system for minidrones [↗](#)
- **Best Freshmen of the A.Y.** | Milan, 2017

Milan, 29th June 2024

